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**Supervised Learning:**

**Pattern Recognition System**

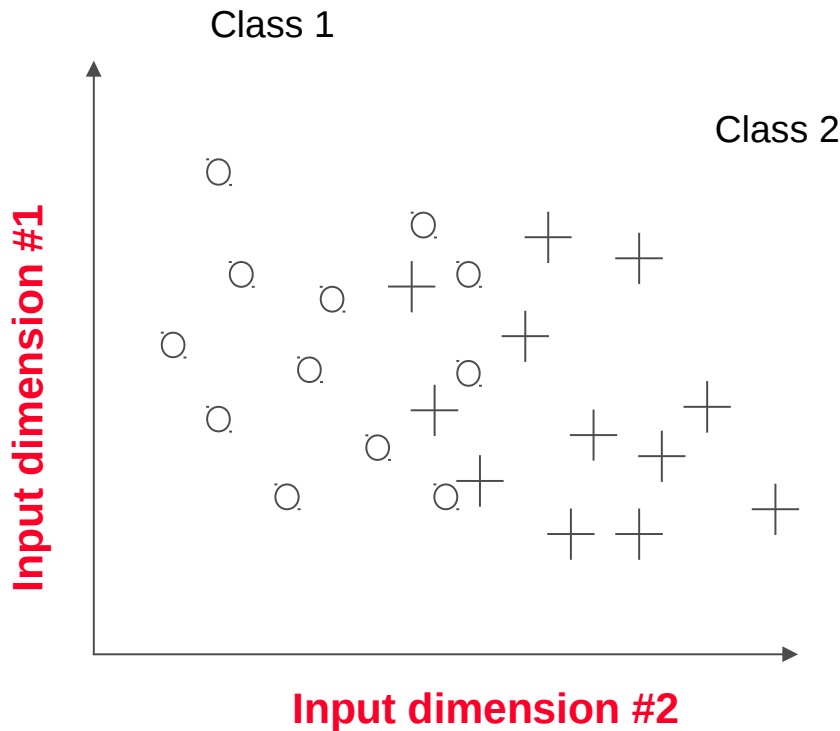
# Supervised Learning

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- **In supervised learning, the aim is to learn a mapping from the input to an output whose correct values are provided by a supervisor.**
- There are many applications of machine learning in *pattern recognition*.
  - *optical character recognition*
  - *face recognition*
  - *medical diagnosis (ECG, EEG signal classification)*
  - *speech recognition*
  - *time-series prediction*

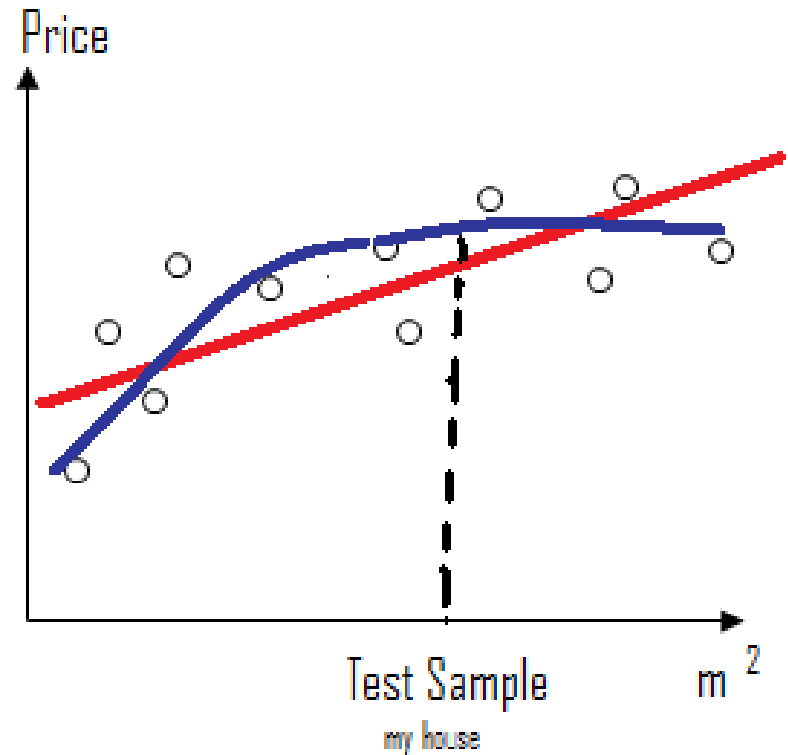
# Supervised Learning

- Training Set
- Input Variable / “Features”
- Output Variable / “Target”



## Classification

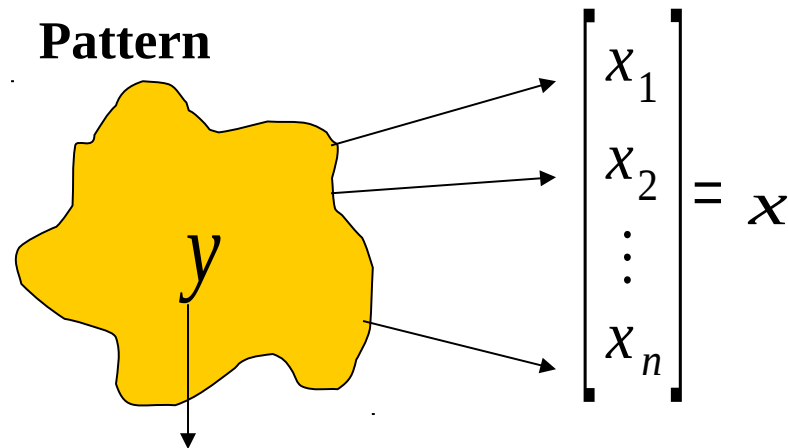
Target: Discrete



## Regression

Target: Continues

# Basic concepts



**Feature vector**  $x \in X$

- A vector of observations (measurements).

-  $x$  is a point in feature space  $X$ .

**Hidden state**  $y \in Y$

- Cannot be directly measured.

- Patterns with equal hidden state belong to the same class.

**Task**

- To design a classifier (decision rule)  $q: X \rightarrow Y$

which decides about a hidden state based on an observation.

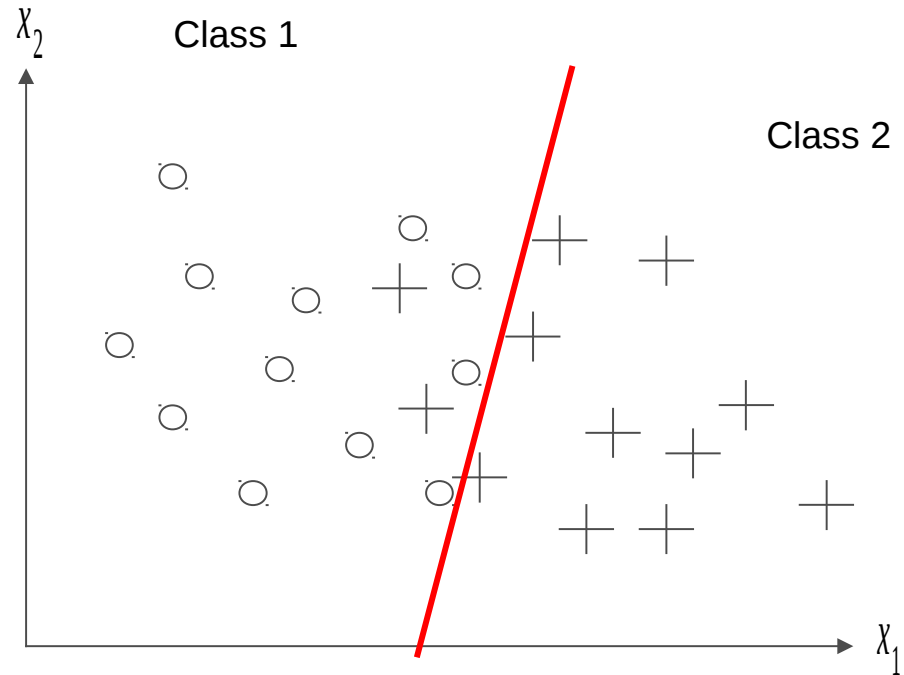
$$y = q(x) = a_0 + a_1 x_1 + \dots + a_n x_n$$

# Hypothesis (q) \_ Decision Surface

$$y = q(x) = a_0 + a_1 x_1 + \dots + a_n x_n$$

$$y = q(x) = \sum_{i=0}^{i=n} a_i x_i$$

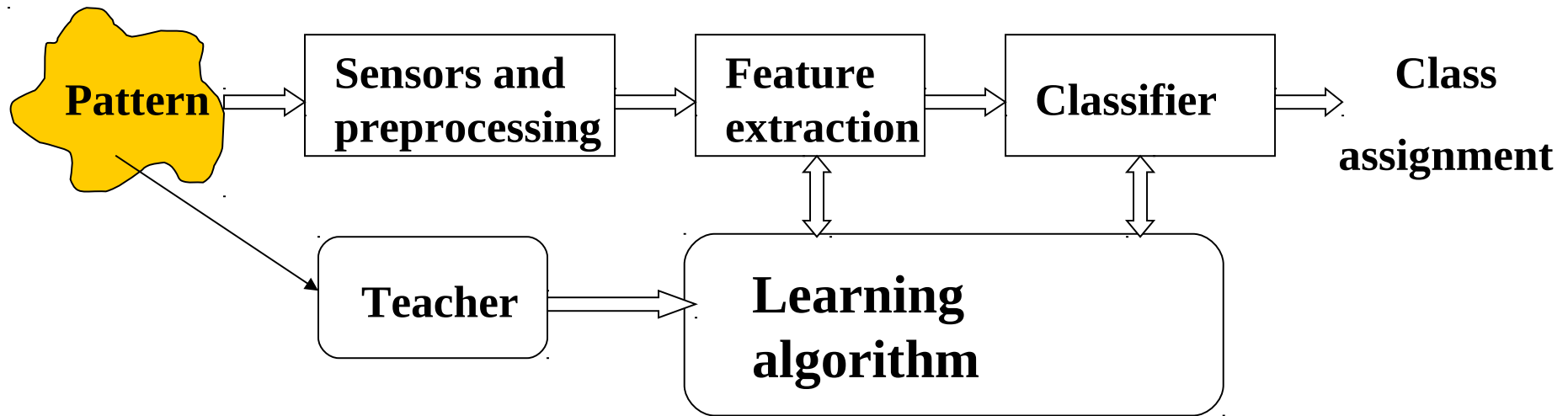
**N:** number of features



$$y = h(x) = q(x) = a_0 + a_1 x_1 + a_2 x_2$$

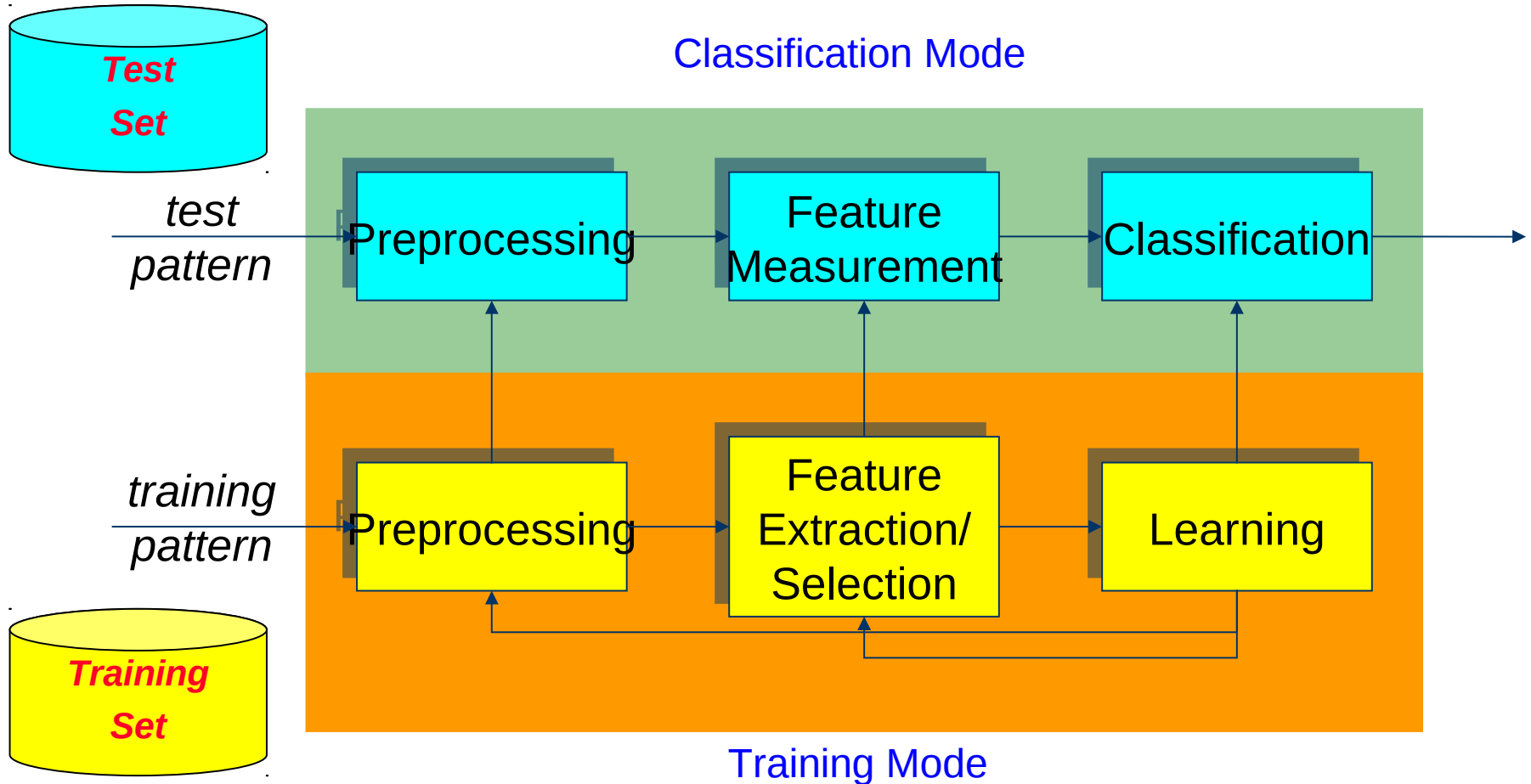
# Components of PR system

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- **Sensors and preprocessing.**
- **A feature extraction aims to create discriminative features good for classification.**
- **A classifier.**
- **A teacher provides information about hidden state - supervised learning.**
- **A learning algorithm sets PR from training examples.**

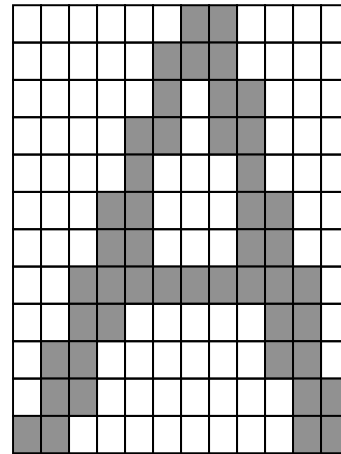
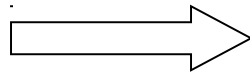
# Pattern Recognition System



# Template Matching

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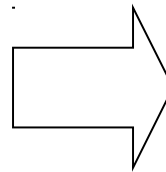
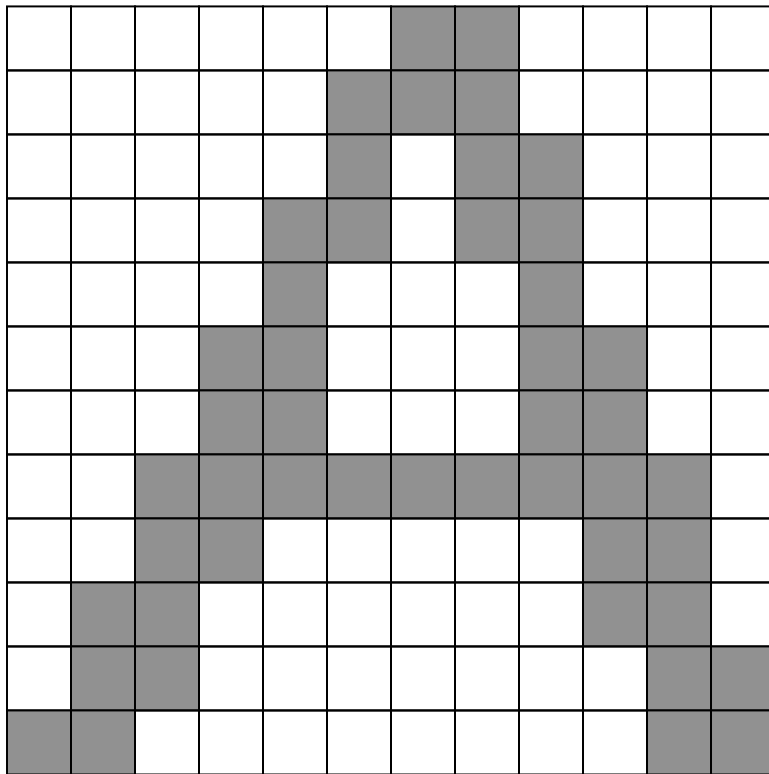
Image is converted into 12x12 bitmap.





# Template Matching

Bitmap is represented by 12x12-matrix or by 144-vector with 0 and 1 coordinates.



0	0	0	0	0	0	1	1	0	0	0	0
0	0	0	0	0	1	1	1	0	0	0	0
0	0	0	0	0	1	0	1	1	0	0	0
0	0	0	0	1	1	0	1	1	0	0	0
0	0	0	0	1	0	0	0	1	0	0	0
0	0	0	1	1	0	0	0	1	1	0	0
0	0	0	1	1	0	0	0	1	1	0	0
0	0	1	1	1	1	1	1	1	1	1	0
0	0	1	1	0	0	0	0	0	1	1	0
0	1	1	0	0	0	0	0	0	1	1	0
0	1	1	0	0	0	0	0	0	0	1	1
1	1	0	0	0	0	0	0	0	0	1	1

# Template Matching

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**Training samples – templates with corresponding class:**

$$t_1 = \{ (0,0,0,0,1,1,\dots,0), 'A' \}$$

$$t_2 = \{ (0,0,0,0,0,1,\dots,0), 'A' \}$$

.....

$$t_k = \{ (0,0,1,1,1,1,\dots,0), 'B' \}$$

.....

**Template of the image to be recognized:**

$$T = \{ (0,0,0,0,1,1,\dots,0), 'A' \}$$

**Algorithm:**

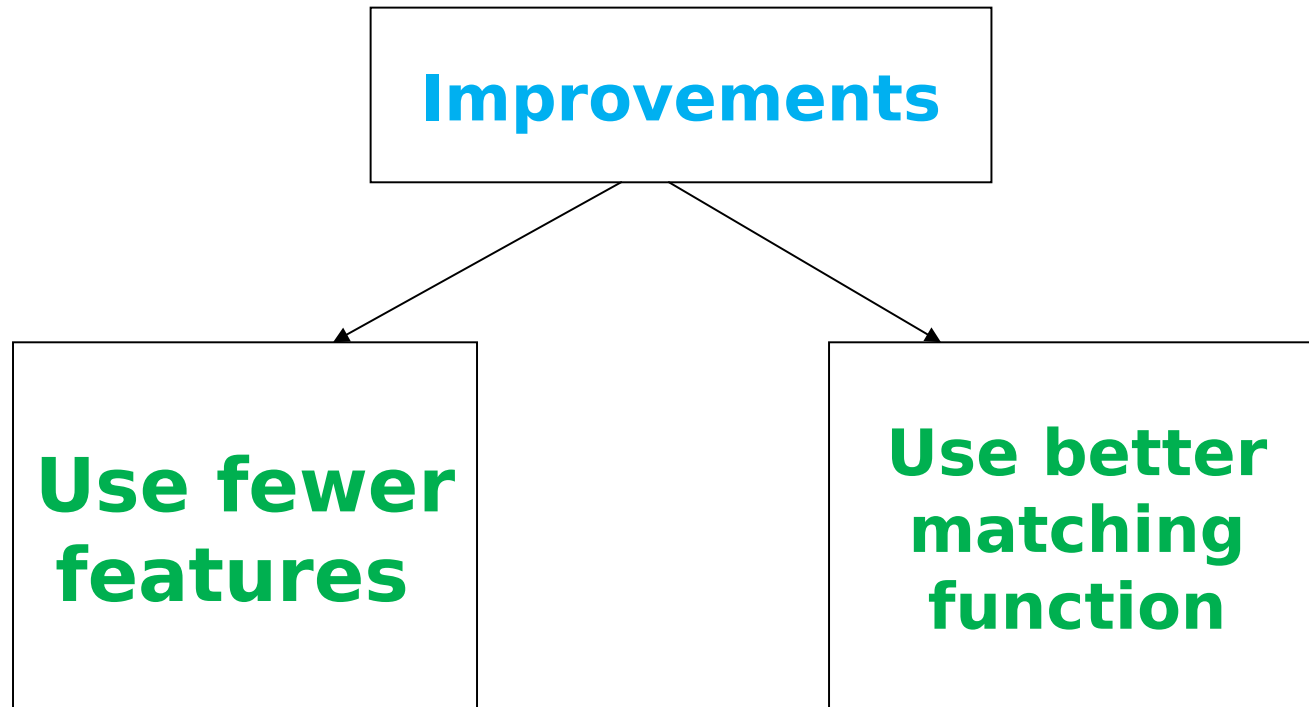
1. Find  $t_i$ , so that  $t_i = T$ .
2. Assign image to the same class as  $t_i$ .

# Template Matching

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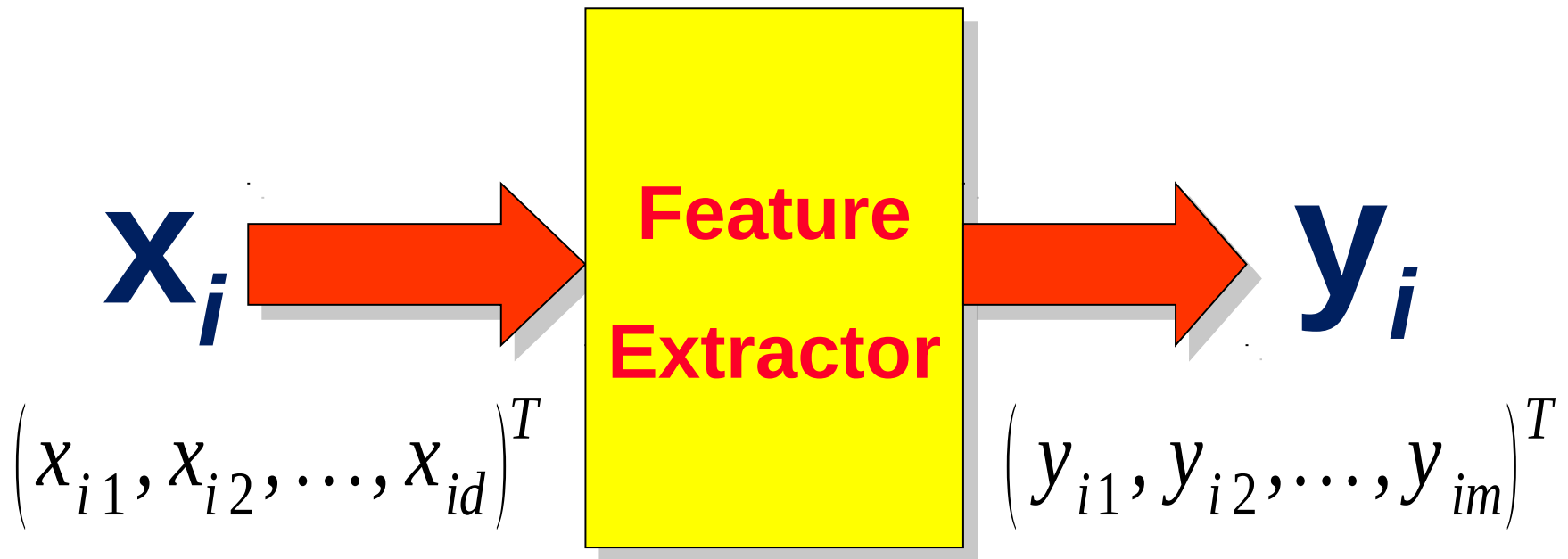
Number of templates to store:  $2^{144}$

If fewer templates are stored, some images might not be recognized.



# Feature Extractor

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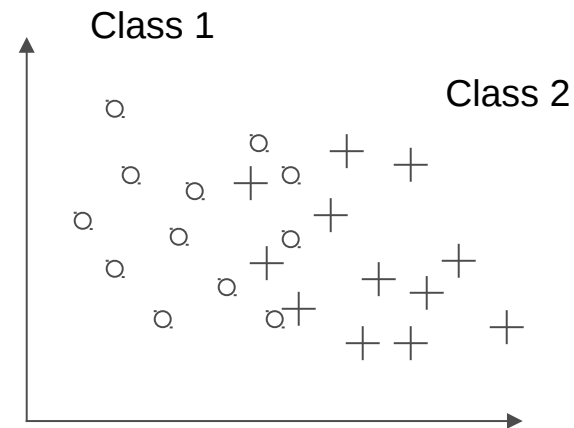
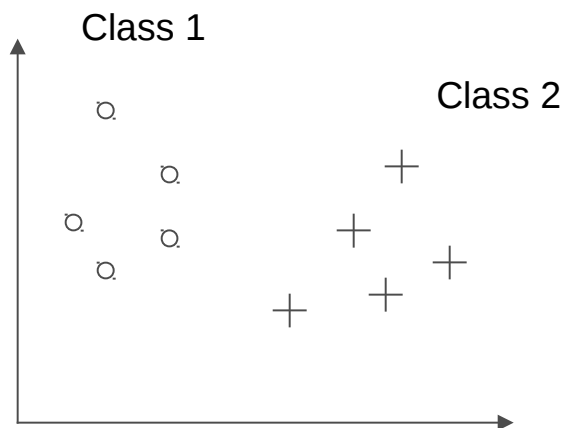


**$m \leq d$ , usually**

# Feature

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- Features are numerically expressed properties of the signal.
- The set of features used for pattern recognition is called feature vector.
- The number of used features is the dimensionality of the feature vector.
- n-dimensional feature vectors can be represented as points in n-dimensional feature space.



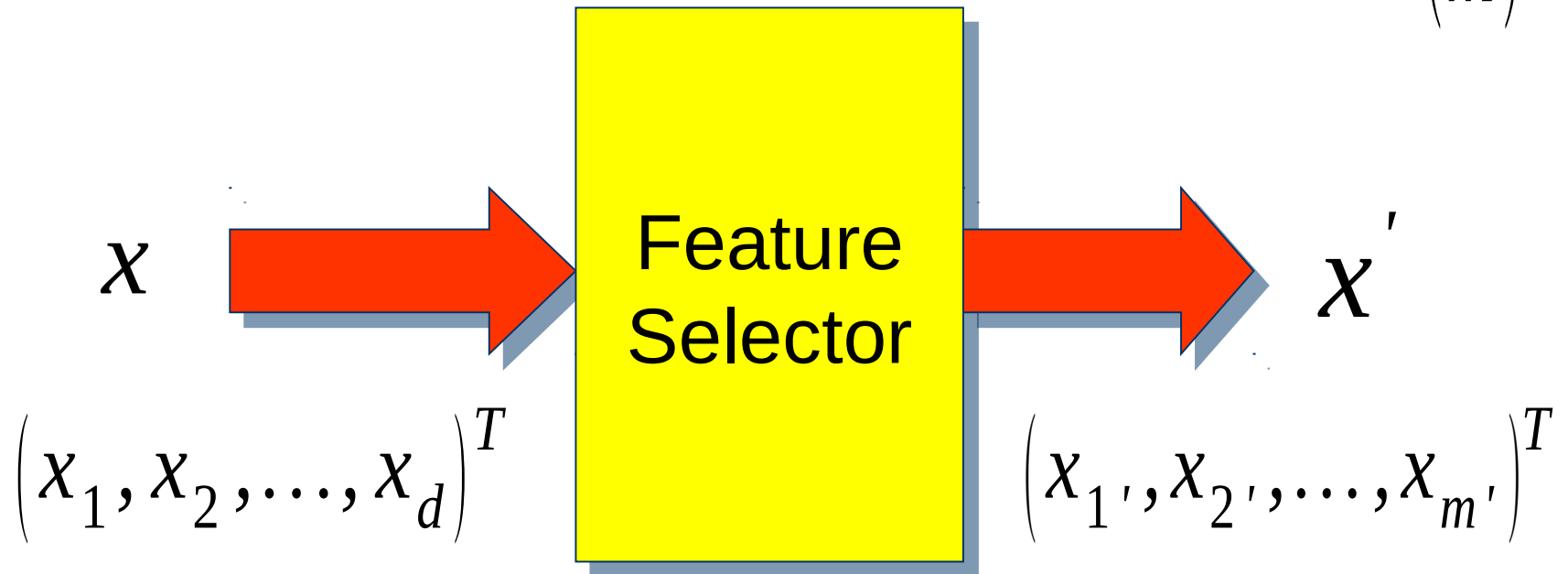
# Some Important Methods

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- Principal Component Analysis (PCA)
    - or Karhunen-Loeve Expansion
  - Independent Component Analysis (ICA)
  - Factor Analysis
  - Discriminate Analysis
- } Linear Approaches
- Kernel PCA
  - Multidimensional Scaling (MDS)
- } Nonlinear Approaches
- Feed-Forward Neural Networks
  - Self-Organizing Map
- } Neural Networks

# Feature Selector • Feature Fusion

# possible Selections  $\binom{d}{m}$



$m \leq d$ , usually

# Classification: Terminology

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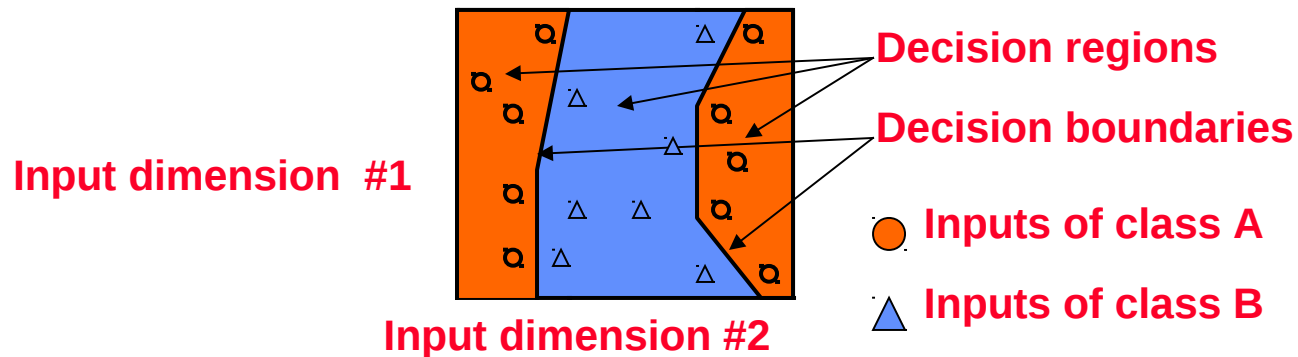


**A *classifier* can be viewed as a function of block. A classifier assigns one class to each point of the input space. The input space is thus partitioned into disjoint subsets, called *decision regions*, each associated with a class.**



# Classification: Terminology (cont.)

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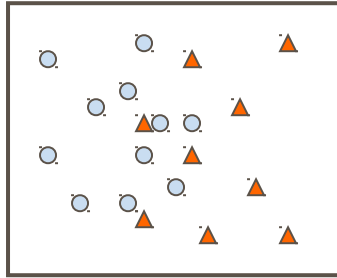


- **The way a classifier classifies inputs is defined by its decision regions.**
- **The borderlines between decision regions are called *decision-region boundaries* or simply *decision boundaries*.**

# Classification: Terminology (cont.)

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Input dimension #1

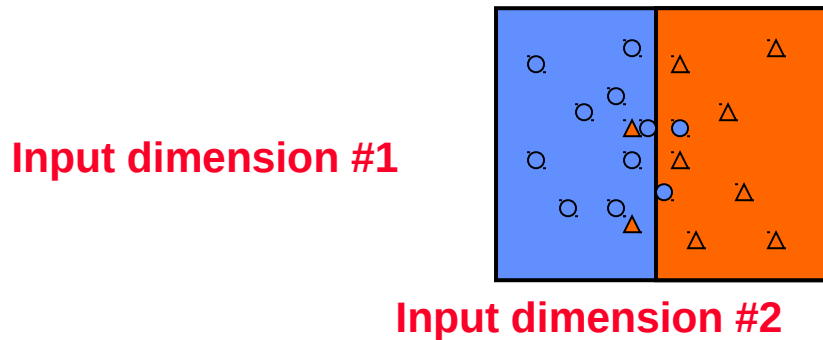


Input dimension #2

In practice, input vectors of different classes are rarely so neatly distinguishable. Samples of different classes may have same input vectors. Due to such a *uncertainty*, areas of input space can be clouded by a mixture of samples of different classes.

# Classification: Terminology (cont.)

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- The *optimal classifier* is the one expected to produce the least number of misclassifications (**Error Reduction**).
- Such misclassifications are due to uncertainty in the problem rather than a deficiency in the decision regions.

# Classification: Terminology (cont.)

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- A designed classifier is said to **generalize well** if the classifier achieves similar classification accuracy to both training samples and real world samples

Training Error Reduction #  
Generalization

